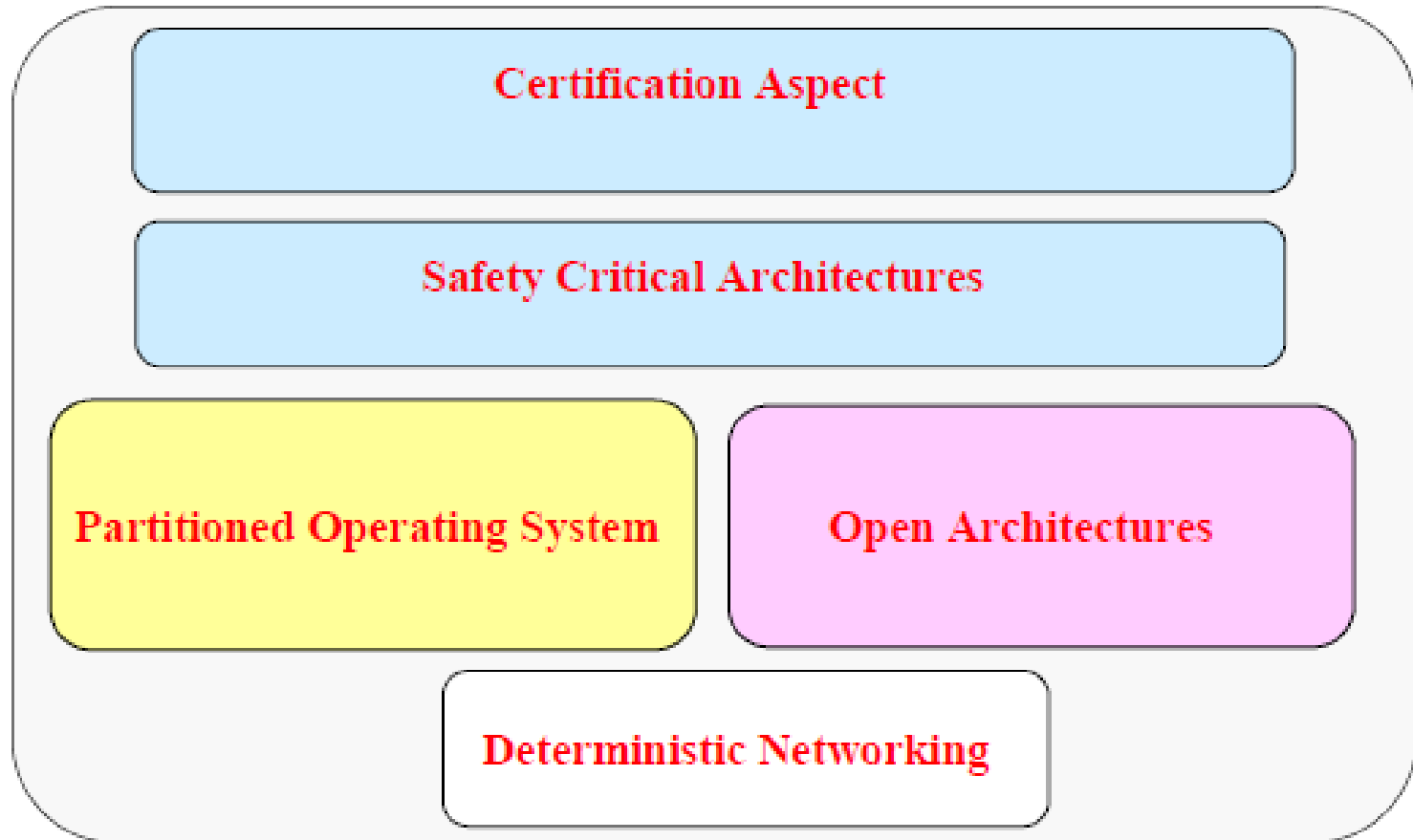


# *From Annex B.2 – Dependable Avionic Computer*

## **Avionic Computing Key Pillars**



# A certified version is required

**The established standards for development of avionics are these:**

**Software: DO-178B (USA)/ED-12 (Europe) and**

**Hardware: DO-254 (USA)/ED-80 (Europe)**

**ED12B-C/DO-178B *Level A* is governing situations where a defect would result in catastrophic accident.**

**Certification is expensive, costing approx. \$40-50 per line of code \*)  
One manufacturer estimates full UAV/RPA code of its new UAV to be 65mill lines of code... (50% more than Windows)**

**\*) Source: <http://www.windriver.com/solutions/aerospace-defense/>**

# DO 178B/ED 12 Software restrictions

- **Compilers are limited to certified ADA or C,**
- **Operating system must be certified RTOS\***
- **Choice of hardware is limited (ARINC)**
- **Fully deterministic behaviour is required \*\***
- **No surplus code allowed, only net usable code (including subsystems) \*\*\***

**\* Real Time Operatins System**

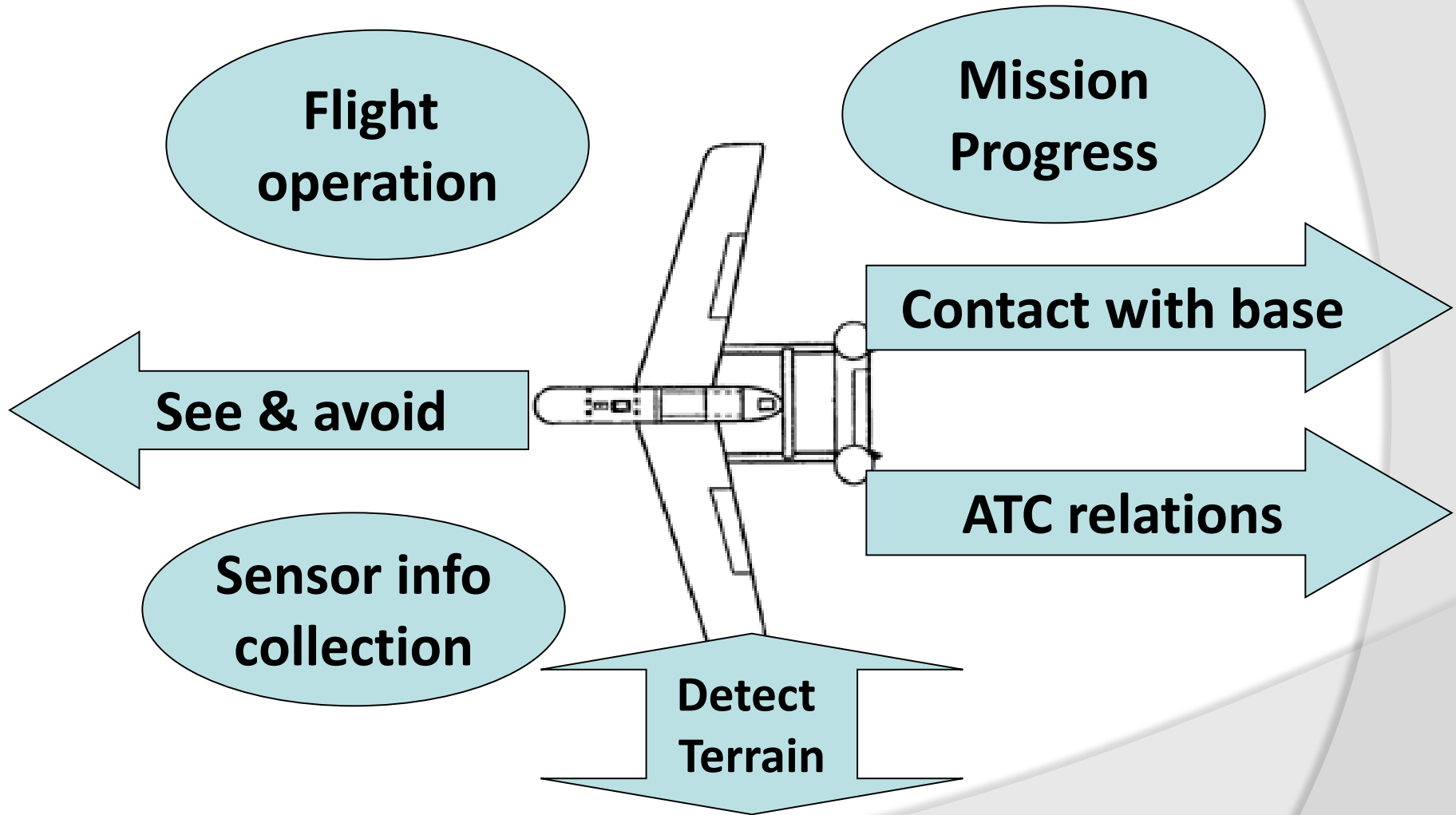
**\*\* Excludes Neural Networks**

**\*\*\* Excludes ordinary DBMS systems**

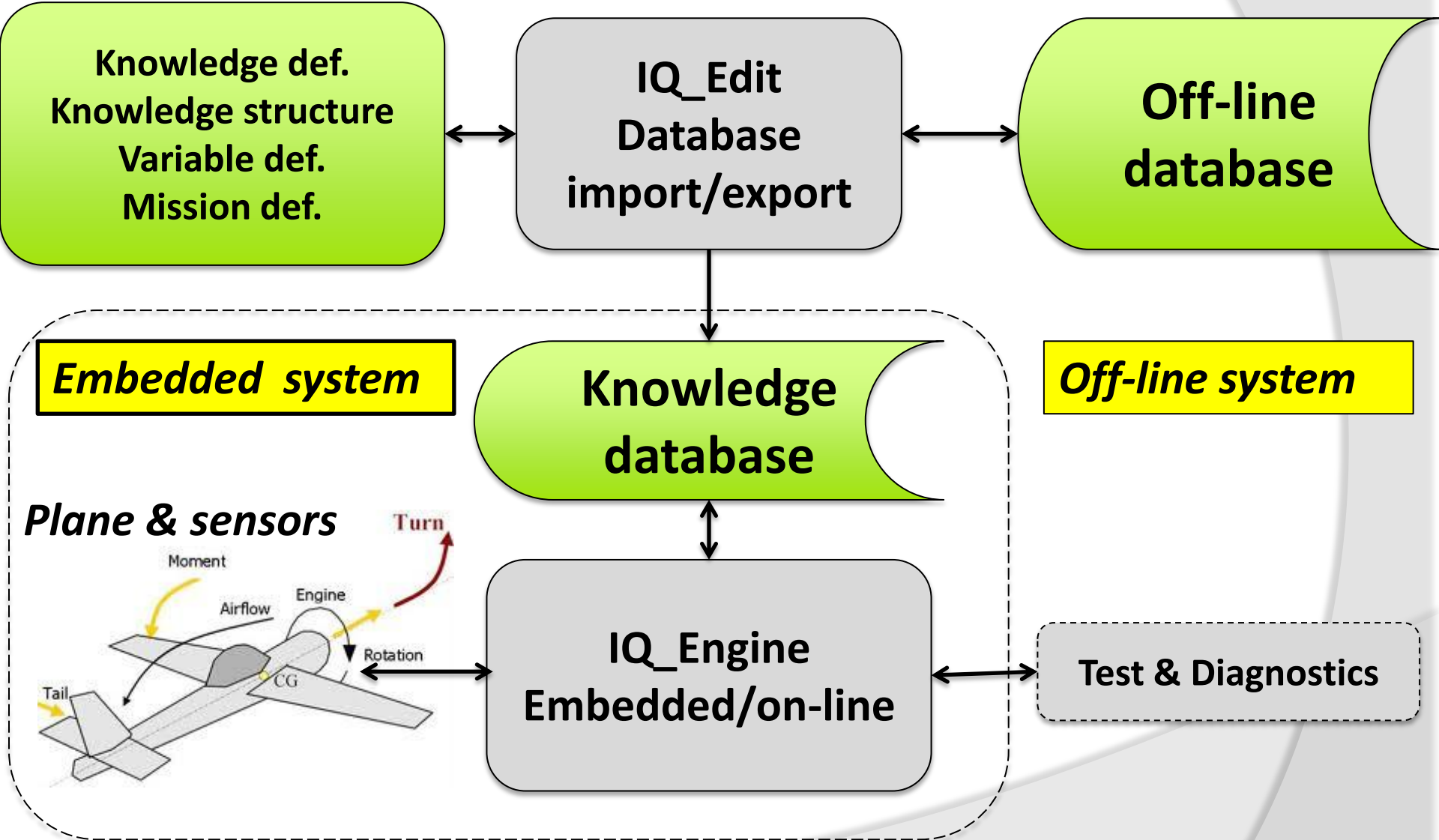
# DO-178B/EB 12 software projects involve this documentation:

- 1. Plan for Software Aspects of Certification (PSAC)*
- 2. Software Development Plan (SDP)*
- 3. Top-level Design Document for the RTOS (Arinc653)*
- 4. Detailed Design Document for (Arinc653)*
- 5. Tested software system executable as standalone system*
- 6. Test suite for acceptance test and Q&S verification*
- 7. Manuals & Certification Evidence*
- 8. Regular Reporting of progress*

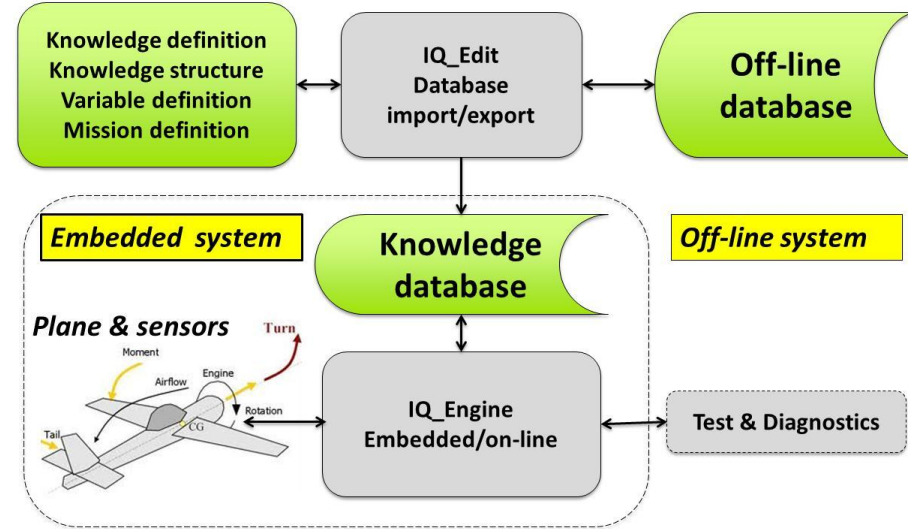
# IQMotor – a task structure example



# IQ\_Engine System Structure



# IQ\_Engine System Structure



- Knowledge can be made manually or automated on the ground
- The Knowledge is fragmented into manageable pieces
- Off-line DB is used to create the online Database
- Search Engine gets input from real sensors and ground control station
- Search Engine enquiries the Knowledge database
- On-board Search Engine SW has to be certified
- On-board DB has to be certified
- First certification has same cost of traditional SW certification
- Advantage: after a change, only incremental certification is required. Not necessary re-certify the full Search Engine (and DB)

# Full Demonstrator

**Control variables**

- Flight\_state: 4 State
- AIL\_factor: 0.48 part of full deflection
- pitch\_target: 0.0 degrees
- ELE\_factor: -1.0 -0.6 -0.2
- heading\_target: 0.0 degrees
- RUD\_factor: 0.87 part of full deflection

**Status variables**

- AIL: 0.06 part of full deflection
- ELE: -0.19 part of full deflection
- RUD: 0.12 part of full deflection
- roll\_target: 180.0 degrees
- roll\_diff: -161.43 degrees
- heading\_target: 0.0 degrees
- heading: -46.62 degrees
- heading\_diff: 46.62 degrees
- pitch\_target: 0.0 degrees
- pitch\_diff: -0.67 degrees
- angle\_sideslip: 0.08 degrees
- v\_eas: 0.08 degrees

**Silent Wings**

Alt: 2000 ft (609.6m) TAS: 174.7

Frame rate: 59.88 fps

**IQ\_Engine  
Embedded/on-line**

**Knowledge  
database**

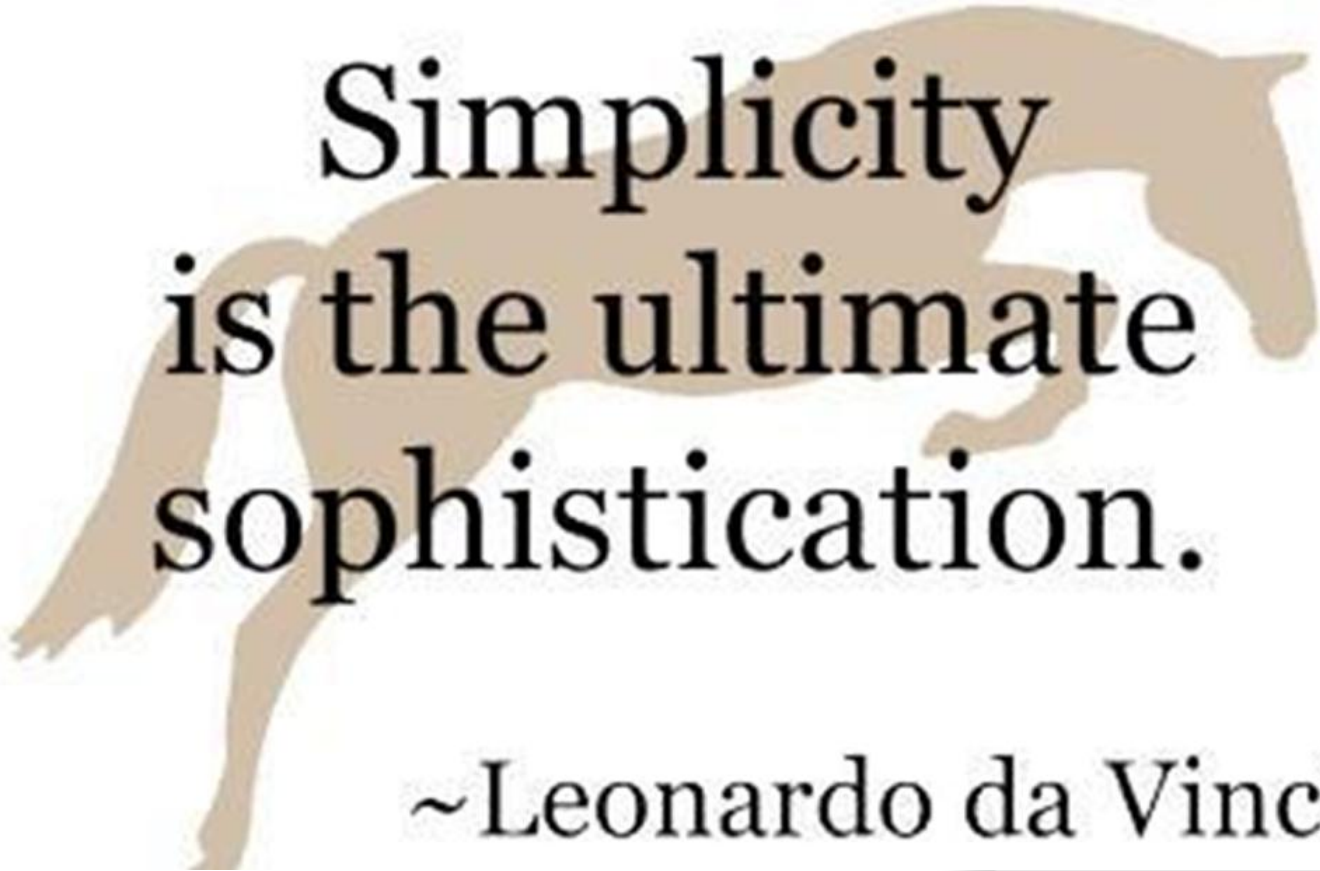
**Ground Control Dashboard**

Heading: 144, Speed: 125 km/h, Time: 04:00, Distance: 150 km



# The key to solving complex systems

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Simplicity  
is the ultimate  
sophistication.

~Leonardo da Vinci